

Simultaneous Transmission of Data and State with Common Knowledge

Yossef Steinberg

Technion—Israel Institute of Technology

ysteinbe@ee.technion.ac.il

Introduction

Outline

- ▶ The general Information Embedding problem
- ▶ Reversible Information Embedding, with and without distortion
- ▶ The common knowledge constraint
- ▶ Main result
- ▶ Example

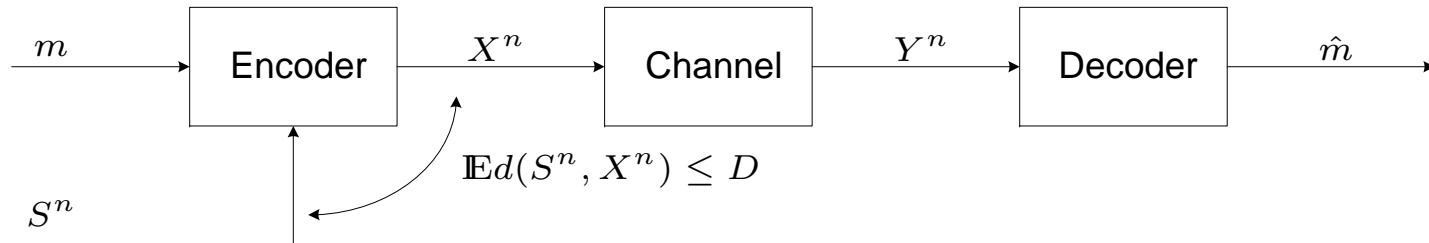
The Information Embedding (IE) Problem

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The CK Constraint

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- ▶ A message m is embedded into host signal S^n , producing data set X^n
- ▶ X^n is transmitted via $P_{Y|X}$ (**attack channel**) to its destination
- ▶ At the destination, a noisy version Y^n of the data set is received, from which m is decoded.
- ▶ In IE, m is embedded into S^n in a manner that is transparent to the unintended observer \Rightarrow a distortion constraint between S^n and X^n
- ▶ **Public IE** – The host S^n is available only at the encoder

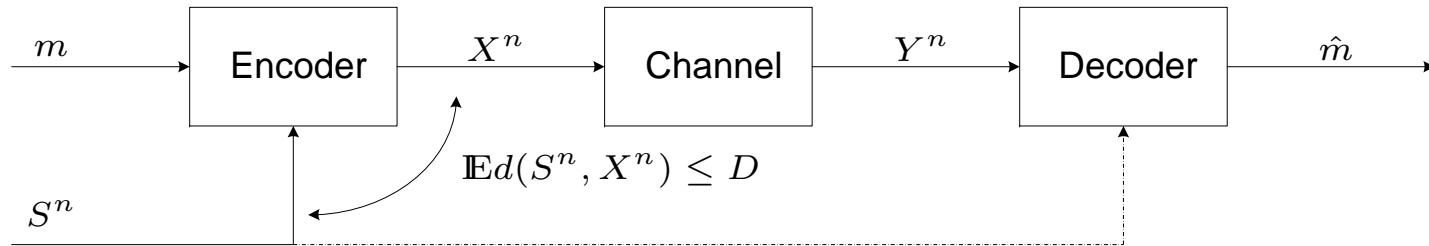
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- ▶ In IE, m is embedded into S^n in a manner that is transparent to the unintended observer \Rightarrow a distortion constraint between S^n and X^n
- ▶ **Public IE** – The host S^n is available only at the encoder
- ▶ **Private IE** – The host S^n is available at both, encoder and decoder

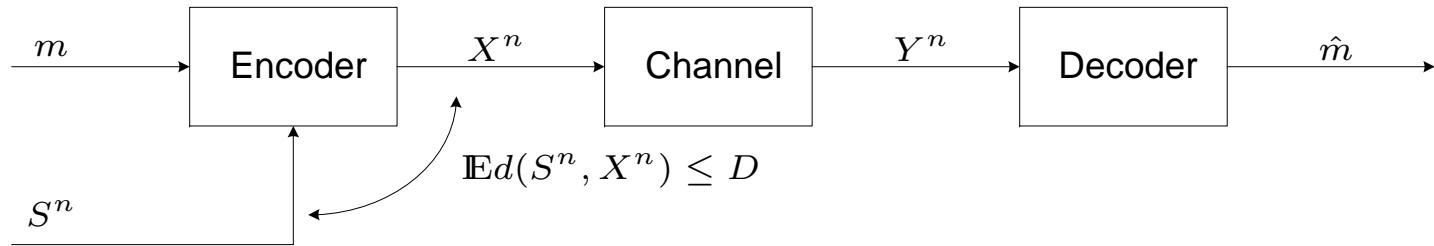
The IE Problem (cont'd)

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- ▶ The distortion constraint is imposed in order to hide the fact that communication (beyond that of S^n) is taking place
- ▶ Classical IE puts emphasis on embedding rate vs. input distortion D .

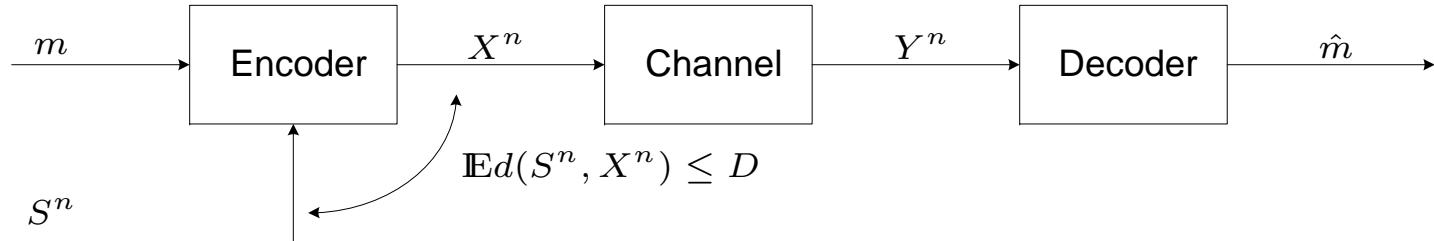
The IE Problem (cont'd)

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- ▶ Classical IE puts emphasis on embedding rate vs. input distortion D .

Closely related to Gel'fand & Pinsker channel [Moulin & O'Sullivan, 2003], due to the distortion constraint. Thus

$$C = \max [I(U; Y) - I(U; S)]$$

where the max is over all $P_{UX|S}$ satisfying the input distortion constraint

$$\mathbb{E}d(S, X) \leq D$$

The IE Problem (cont'd)

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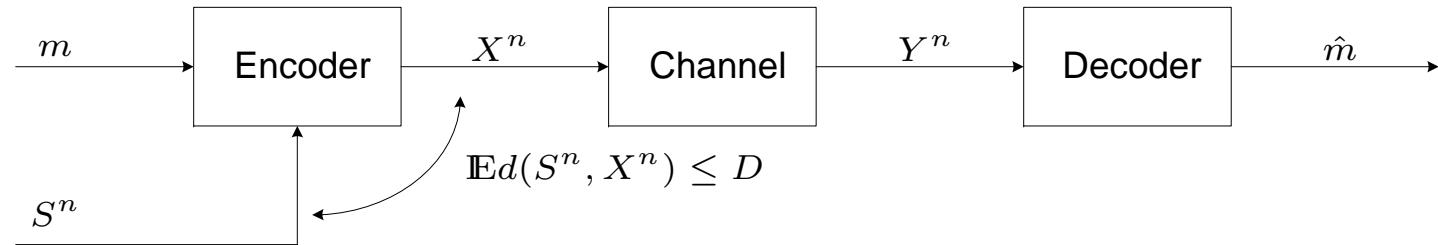
► The Information

Embedding (IE) Problem

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Classical IE – embedding rate vs. input distortion:

$$C = \max_{\mathbb{E}d(S, X) \leq D} [I(U; Y) - I(U; S)]$$

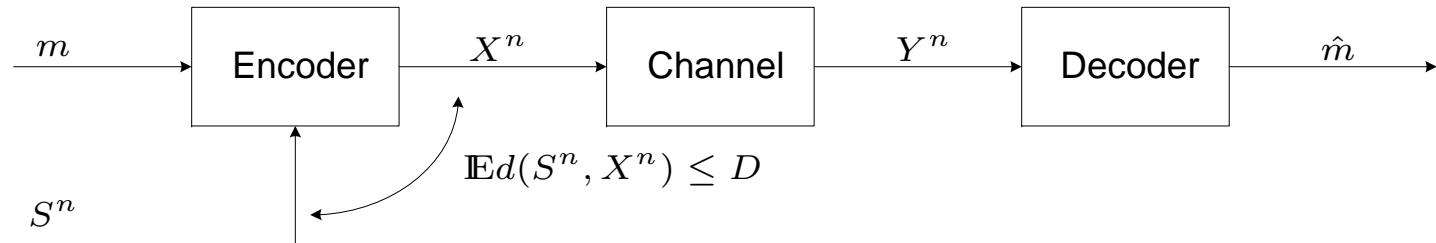
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Classical IE – embedding rate vs. input distortion:

$$C = \max_{\mathbb{E}d(S, X) \leq D} [I(U; Y) - I(U; S)]$$

- ▶ The host S^n is of value at the destination (the reason for communicating from the first place)
- ▶ The destination obtains a noisy version of the data set X^n

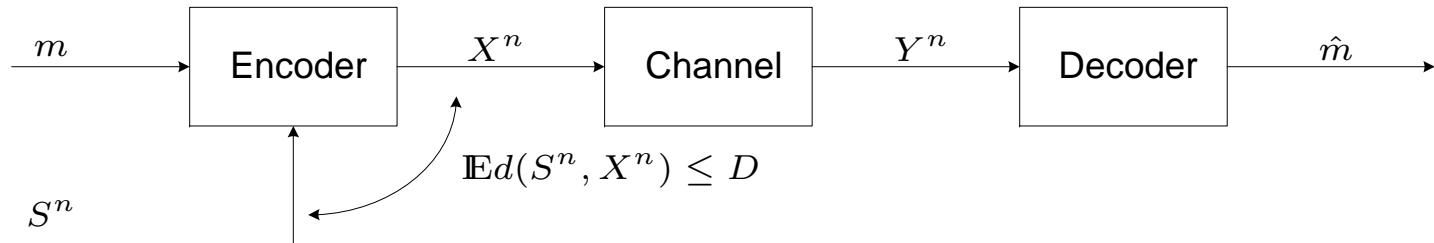
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Classical IE – embedding rate vs. input distortion:

$$C = \max_{\mathbb{E}d(S, X) \leq D} [I(U; Y) - I(U; S)]$$

- ▶ The host S^n is of value at the destination (the reason for communicating from the first place)
- ▶ The destination obtains a noisy version of the data set X^n

Some applications cannot tolerate high distortion at the destination
(e.g., medical imagery).

⇒ Reversible Information Embedding

Reversible IE (with and without distortion)

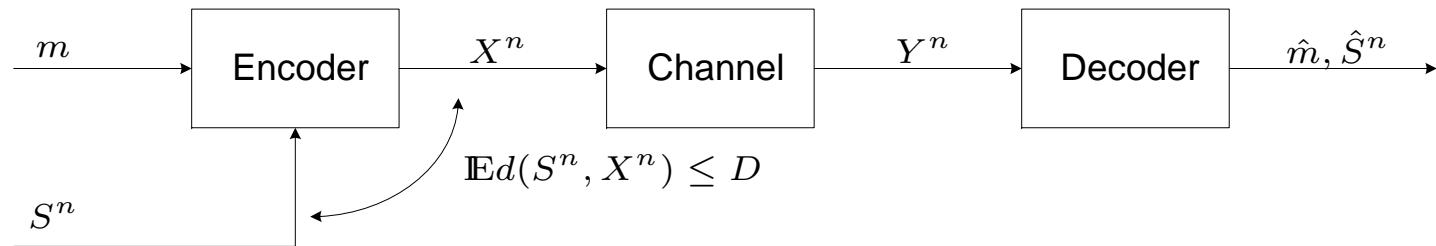
[Fridrich, Goljan, Du SPIE 2002], [Kalker & Willems, 2002]

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In reversible IE (RIE), an additional constraint is imposed, that S^n can be faithfully restored from Y^n . The constraint $\mathbb{E}d(S, X) \leq D$ is still relevant

$$C = \max H(X) - H(S) \quad (\text{no attack channel, Kalker \& Willems})$$

$$C = \max I(X; Y) - H(S) \quad (\text{with channel, Kalker \& Willems, Kotagiri \& Laneman '05})$$

Reversible IE (cont'd)

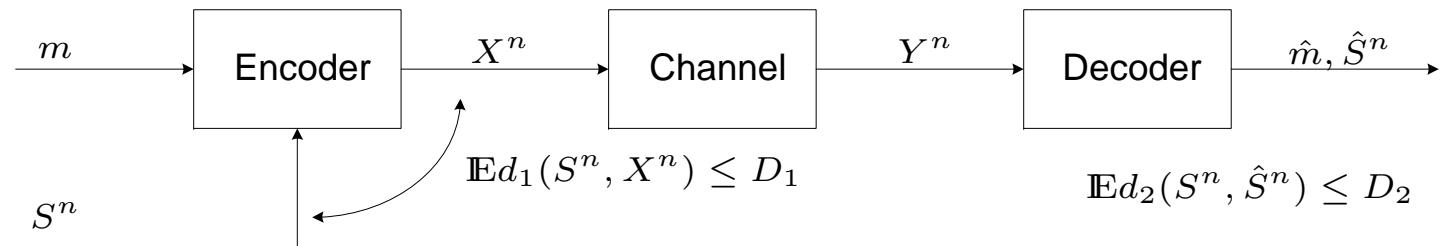
With distortion (Sutivong et. al. 2002, 2005)

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We end up with two distortion constraints. An achievable rate

$$R = \max[I(U; Y) - I(U; S)]$$

where the max is over all $P_{X, U|S}$ such that

$$\mathbb{E}d_1(S, X) \leq D_1$$

$$\mathbb{E}d_2(S, \phi(U, Y)) \leq D_2$$

for some function $\phi : \mathcal{U} \times \mathcal{Y} \rightarrow \hat{\mathcal{S}}$.

Reversible IE (cont'd)

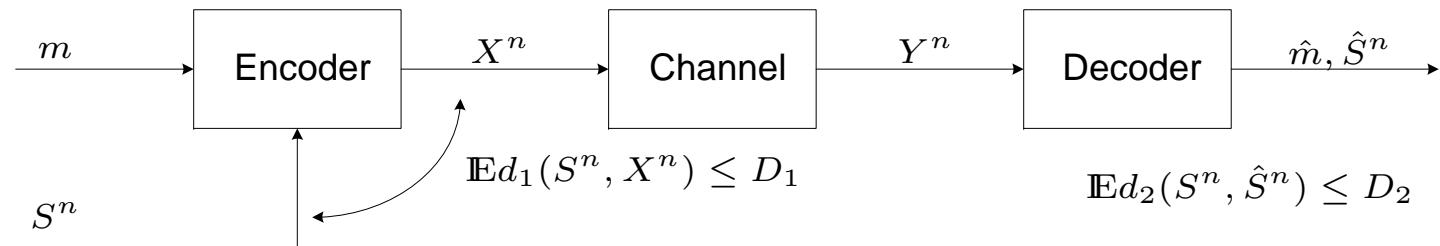
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We end up with two distortion constraints. An achievable rate

$$R = \max[I(U; Y) - I(U; S)] \geq 0$$

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Reversible IE (cont'd)

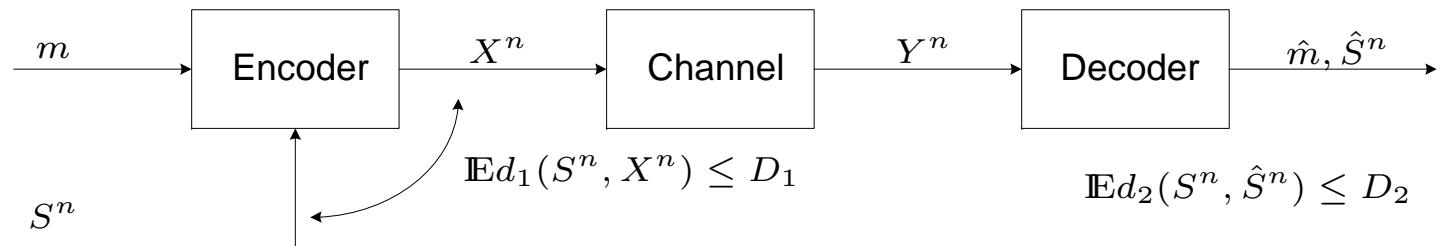
With distortion (Sutivong et. al. 2002, 2005)

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for some function $\phi : \mathcal{U} \times \mathcal{Y} \rightarrow \hat{\mathcal{S}}$. Solved for the Gaussian case (Sutivong et. al. 2005). Contributions by Merhav & Shamai 2007, Cover, Kim, and Sutivong 2007.

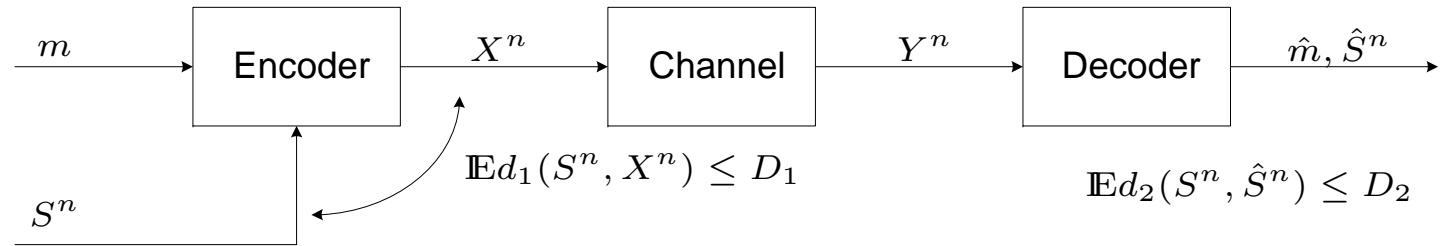
Reversible IE with distortion (cont'd)

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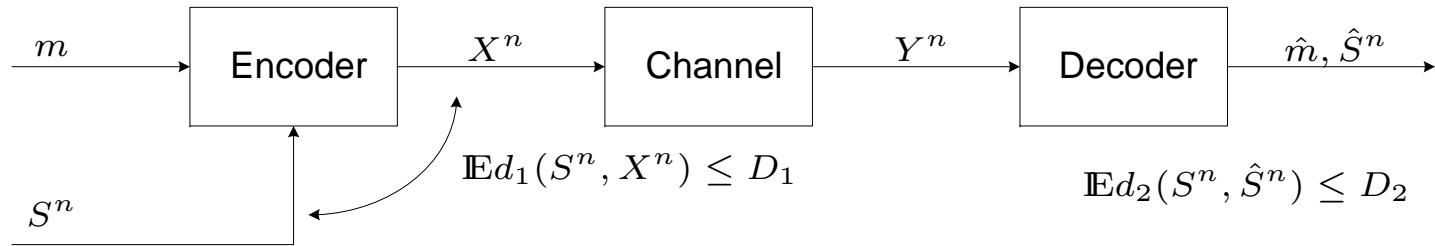
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- ▶ A separation based strategy is suboptimal.
- ▶ Part of the distortion is introduced by the channel noise. Thus the estimated host \hat{S}^n cannot be reproduced at the sender side

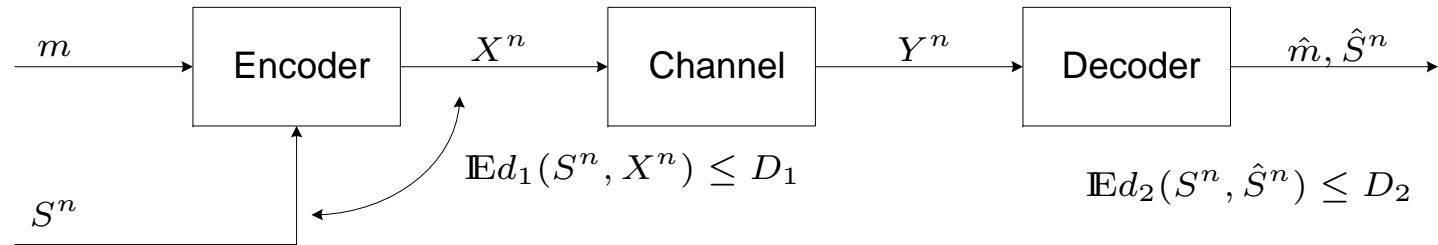
Reversible IE with distortion (cont'd)

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- A separation based strategy is suboptimal.
- Part of the distortion is introduced by the channel noise. Thus the estimated host \hat{S}^n cannot be reproduced at the sender side

In some applications, this is a drawback.

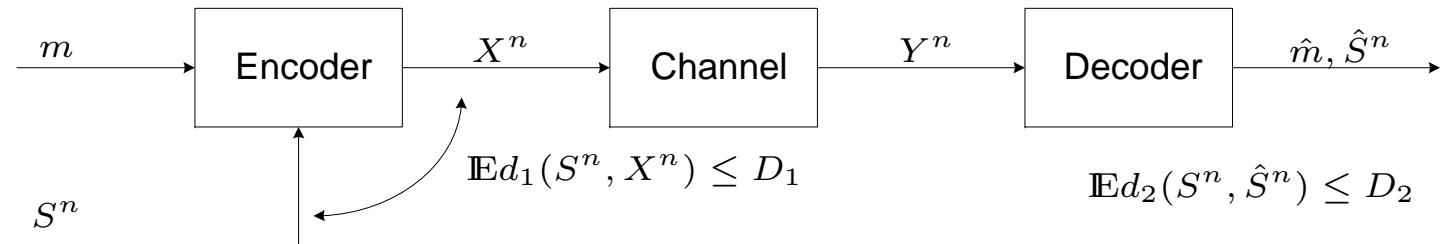
Reversible IE with distortion (cont'd)

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- ▶ Medical data S^n is watermarked (ID, authentication...) and sent to an expert, for consultation.

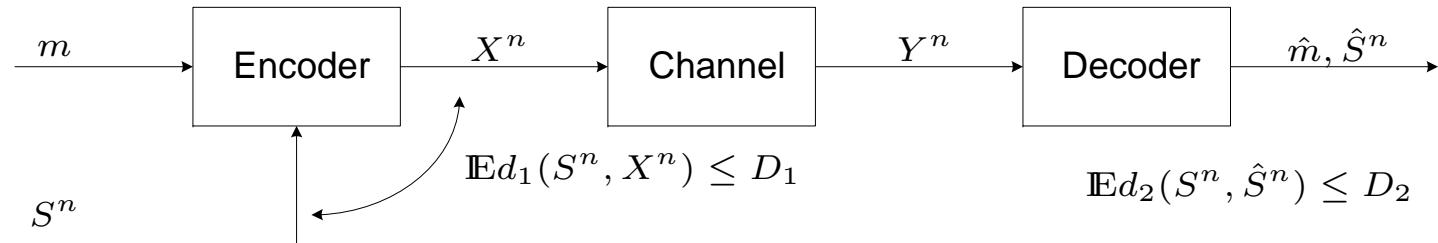
Reversible IE with distortion (cont'd)

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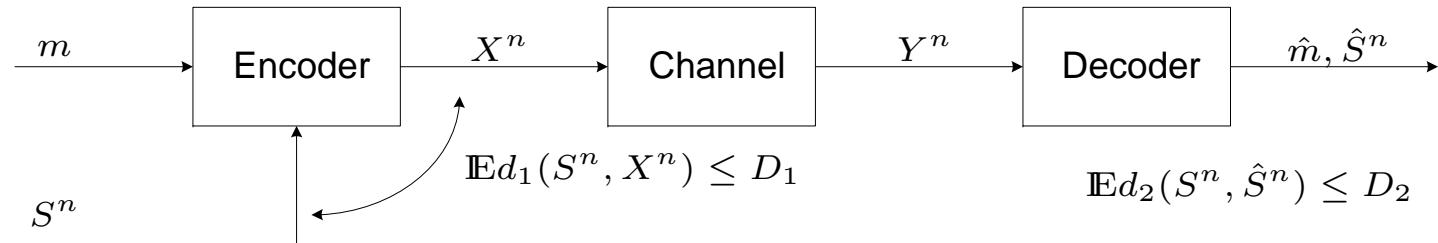
Reversible IE with distortion (cont'd)

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- ▶ Medical data S^n is watermarked (ID, authentication...) and sent to an expert, for consultation.
- ▶ Lossy transmission, due to limitations of the channel.
- ▶ The coding scheme guarantees *average* distortion.
The distortion pattern is not known at the sender side.

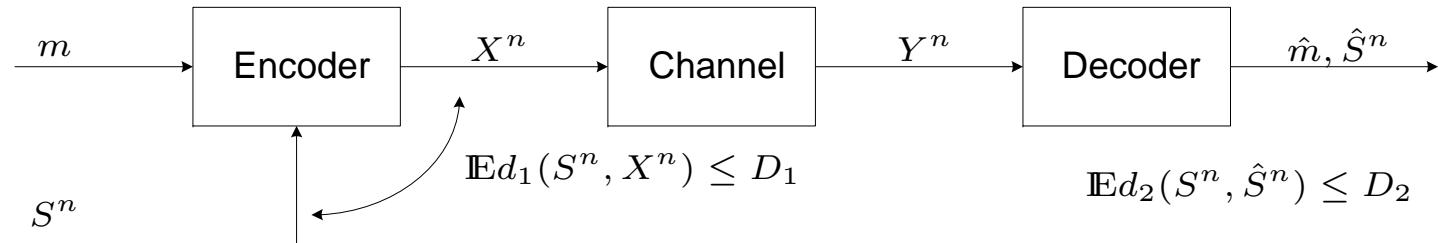
Reversible IE with distortion (cont'd)

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The distortion pattern is not known at the sender side.

Important details can be blurred during transmission. Sender is unaware.

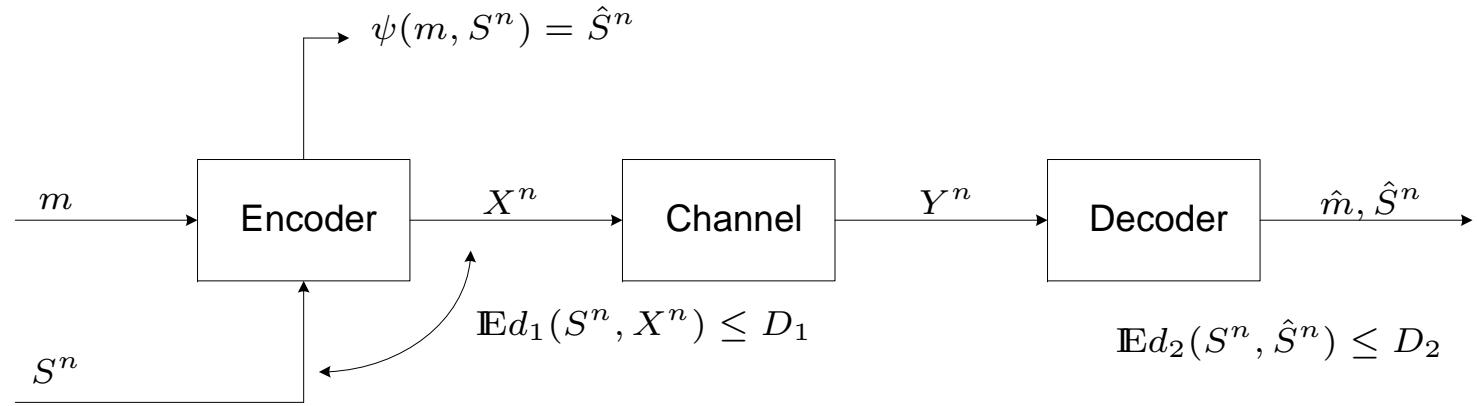
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Devise a coding scheme that enables the sender to produce locally \hat{S}^n .

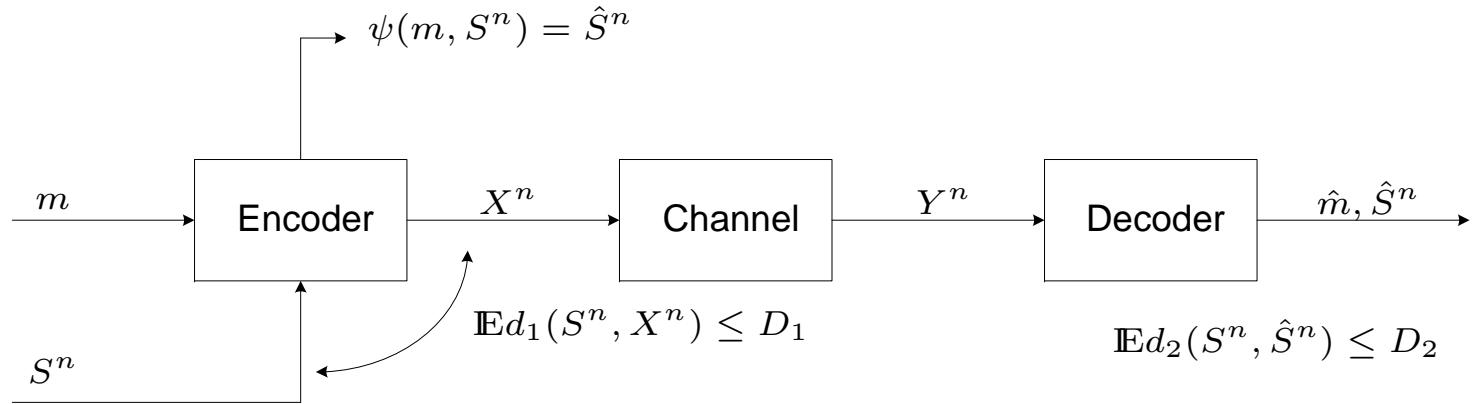
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Devise a coding scheme that enables the sender to produce locally \hat{S}^n .

Role of the common reproduction:

- ▶ Re-transmit in case that the distortion pattern is “bad.”
- ▶ Common reference for the consultation, where the sender and expert (destination) know what the data at the other side look like.

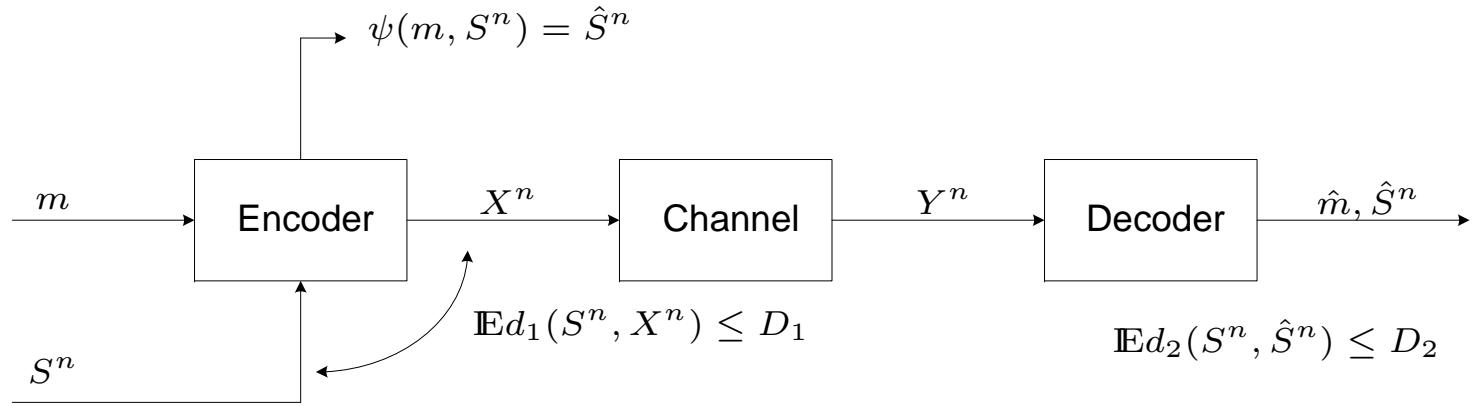
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⇒ *Common Knowledge (CK) constraint*

The Common Knowledge Constraint

Problem Formulation

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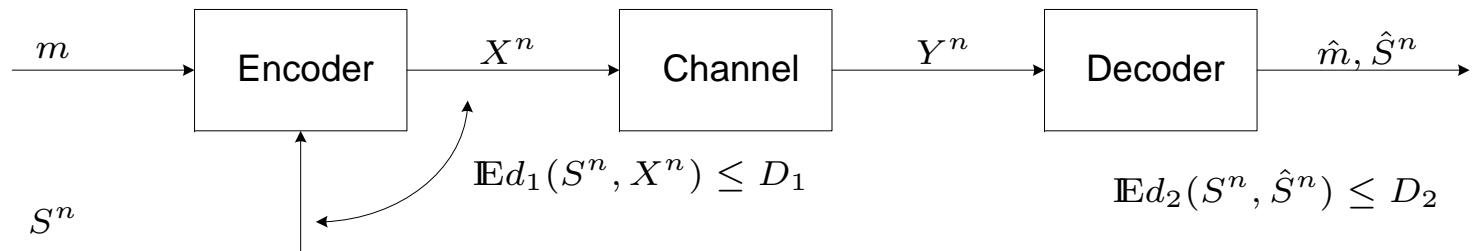
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Problem Formulation

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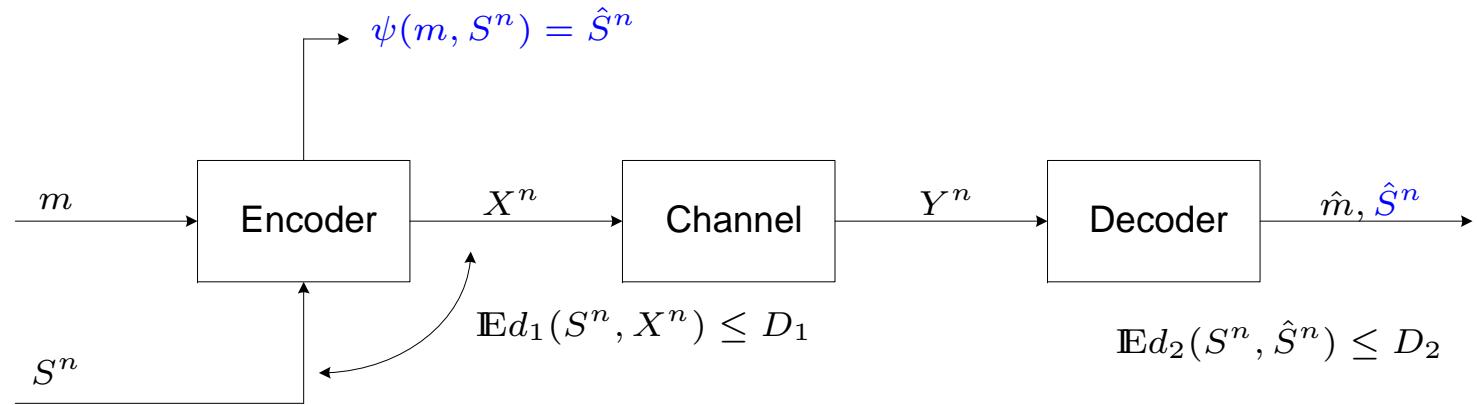
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▶ Problem Formulation

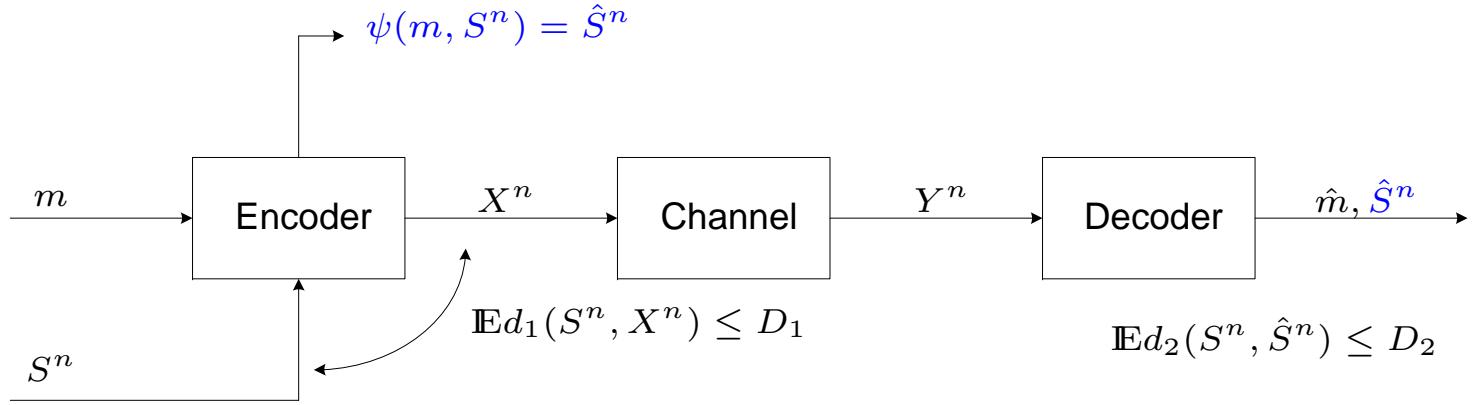
▶ Main Result

▶ Example

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Problem Formulation



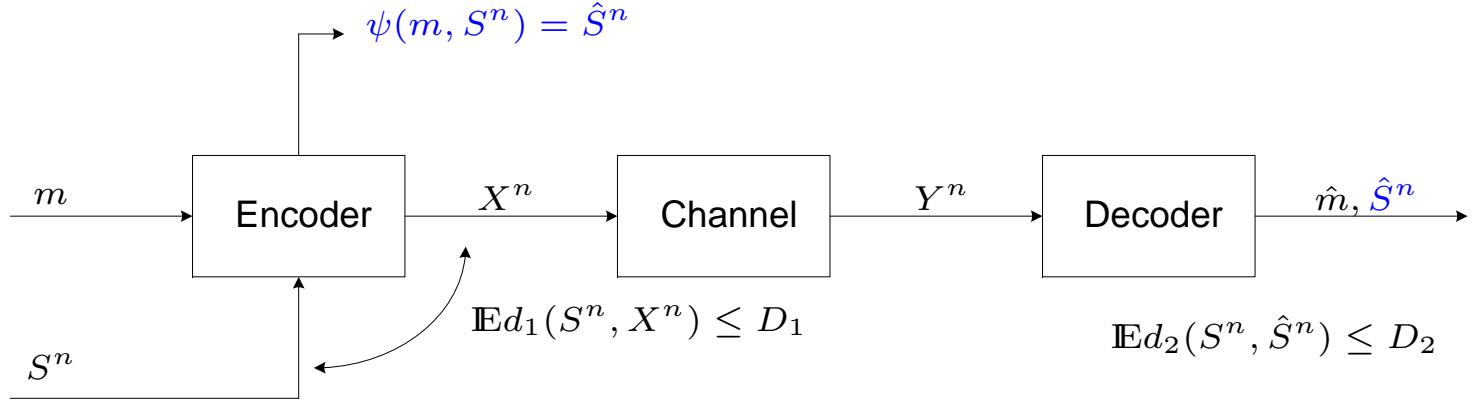
Definition: Let $\mathcal{M} = \{1, 2, \dots, 2^{nR}\}$. An $(n, 2^{nR}, D_1, D_2, \epsilon)$ common knowledge (CK) code consists of

$$\begin{aligned} f : \mathcal{M} \times \mathcal{S}^n &\rightarrow \mathcal{X}^n, && \text{encoder map} \\ g : \mathcal{Y}^n &\rightarrow \mathcal{M}, \quad g_s : \mathcal{Y}^n &\rightarrow \hat{\mathcal{S}}^n & \text{decoding maps} \\ \psi : \mathcal{M} \times \mathcal{S}^n &\rightarrow \hat{\mathcal{S}}^n, && \text{sender reconstruction map} \end{aligned}$$

such that the probability of error is bounded by ϵ , the distortion constraints are satisfied, and

$$P(\psi(m, S^n) \neq \hat{S}^n) \leq \epsilon.$$

Problem Formulation



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Problem Formulation (cont'd)

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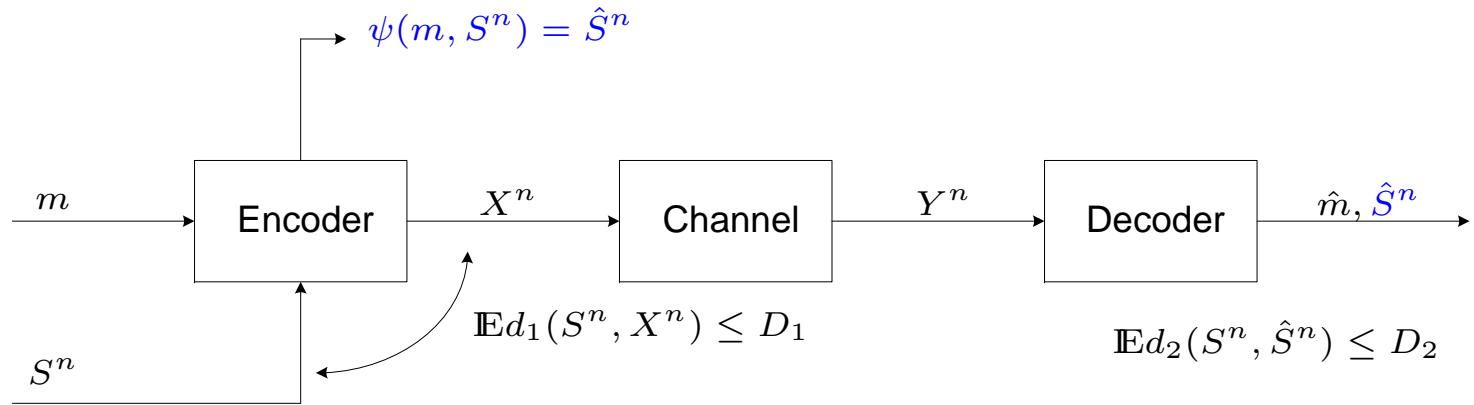
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$$\hat{S}^n = g_s(Y^n)$$

$$P(\psi(m, S^n) \neq \hat{S}^n) \leq \epsilon$$

Problem Formulation (cont'd)

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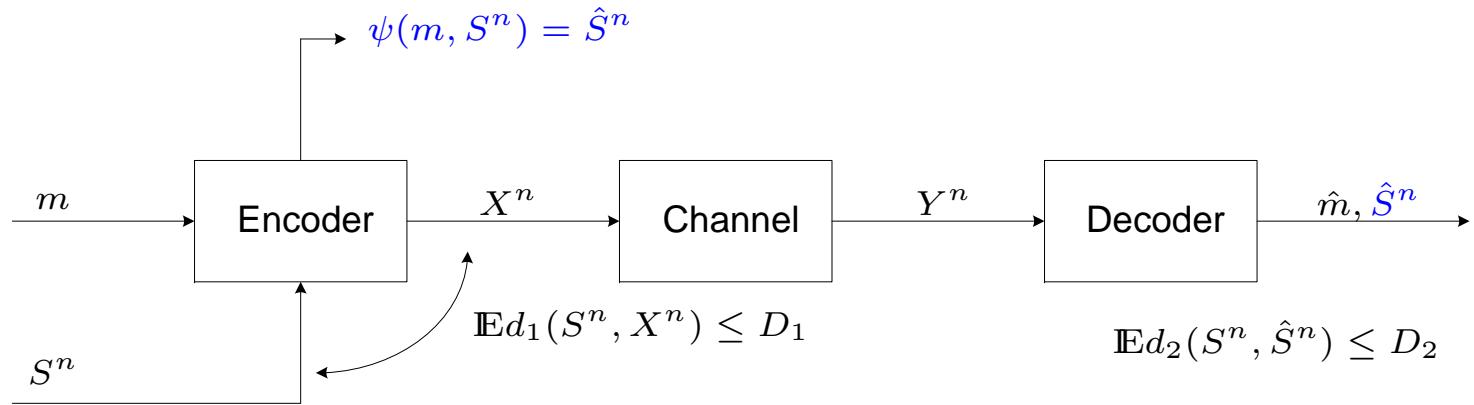
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$$\hat{S}^n = g_s(Y^n)$$

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- ▶ The CK embedding capacity, $C_{ck}(D_1, D_2)$, is the maximal achievable embedding rate with input and output distortions (D_1, D_2) , and arbitrarily small ϵ .

Main Result

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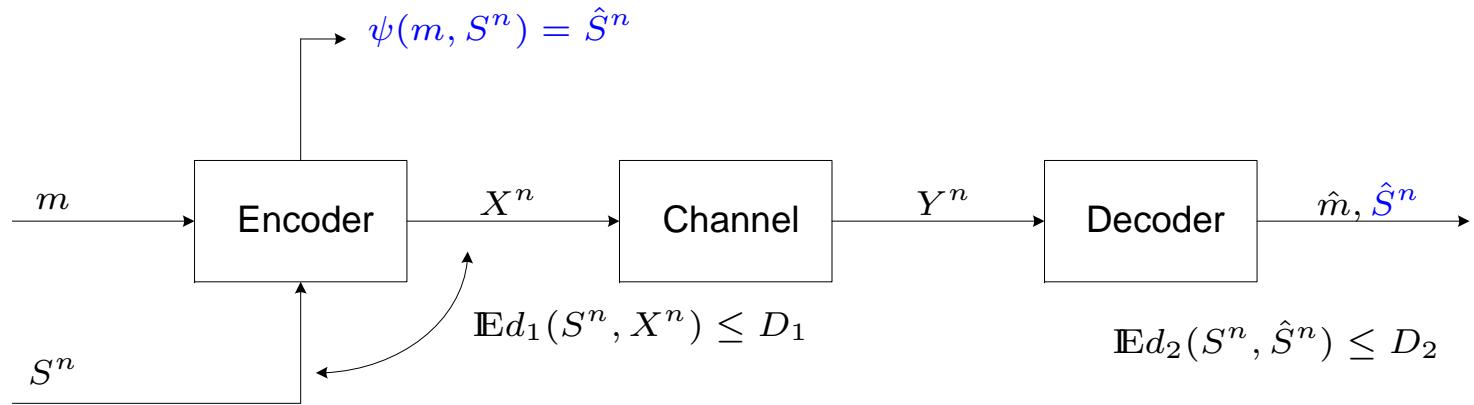
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Theorem 1

$$C_{ck}(D_1, D_2) = \max[I(W; Y) - I(W; S)] \geq 0$$

where the maximum is over all $(W, X) \in W \ominus X \ominus Y$, and $\varphi : \mathcal{W} \rightarrow \hat{\mathcal{S}}$ such that

$$\mathbb{E}d_1(S, X) \leq D_1,$$

$$\mathbb{E}d_2(S, \varphi(W)) \leq D_2.$$

Main Result (cont'd)

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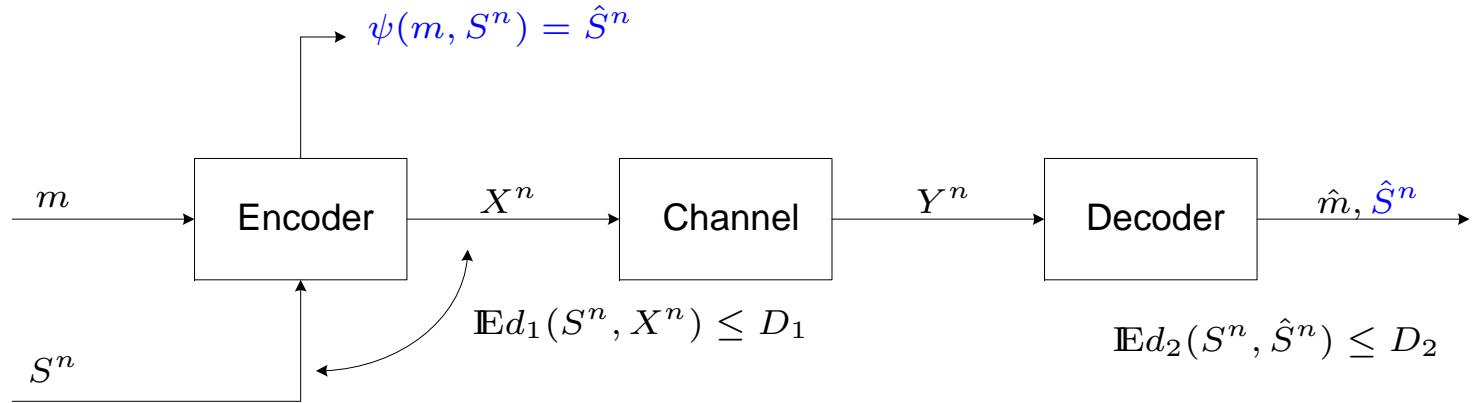
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$$C_{ck}(D) = \max[I(W; Y) - I(W; S)], \quad W \ominus X \ominus Y$$

$$\mathbb{E}d_1(S, X) \leq D_1,$$

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Main Result (cont'd)

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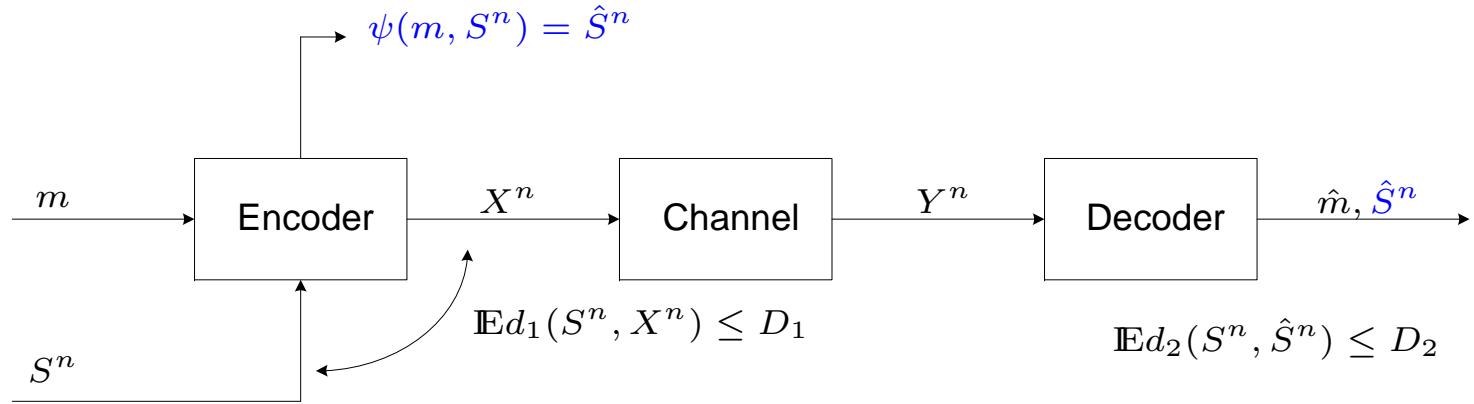
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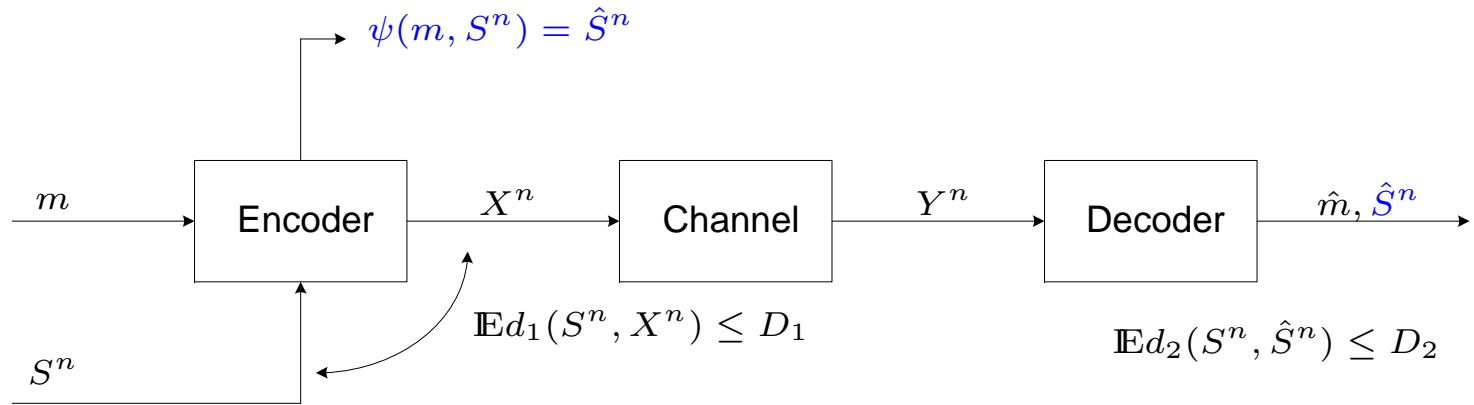
Achievable rate without the CK constraint

$$R = \max[I(U; Y) - I(U; S)], \quad U \ominus X \ominus Y$$

$$\mathbb{E}d_1(S, X) \leq D_1,$$

$$\mathbb{E}d_2(S, \phi(U, \textcolor{red}{Y})) \leq D_2.$$

Main Result (cont'd)



$$C_{ck}(D) = \max[I(W; Y) - I(W; S)], \quad W \ominus X \ominus Y$$

$$\mathbb{E} d_1(S, X) \leq D_1,$$

$$\mathbb{E} d_2(S, \varphi(W)) \leq D_2.$$

- ▶ Construct codewords W^n . Binning operation is as usual
 - ▶ Y^n is used only to resolve the binning. It cannot be used in the estimation phase, to further reduce the distortion.

Main Result (cont'd)

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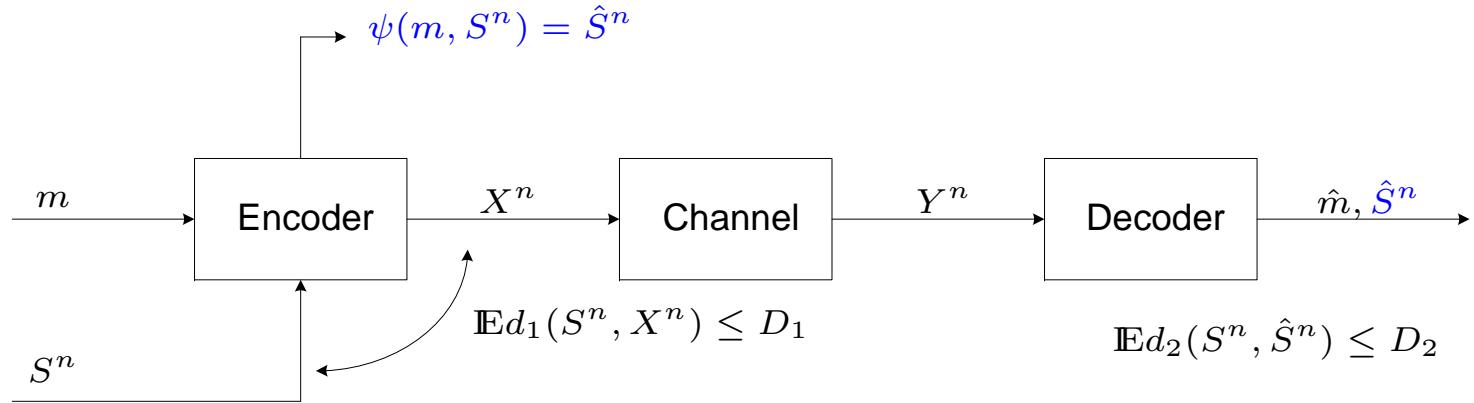
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- ▶ $\max_{\hat{S}} [I(\hat{S}; Y) - I(\hat{S}; S)]$ is achievable, but sub-optimal.

Main Result (cont'd)

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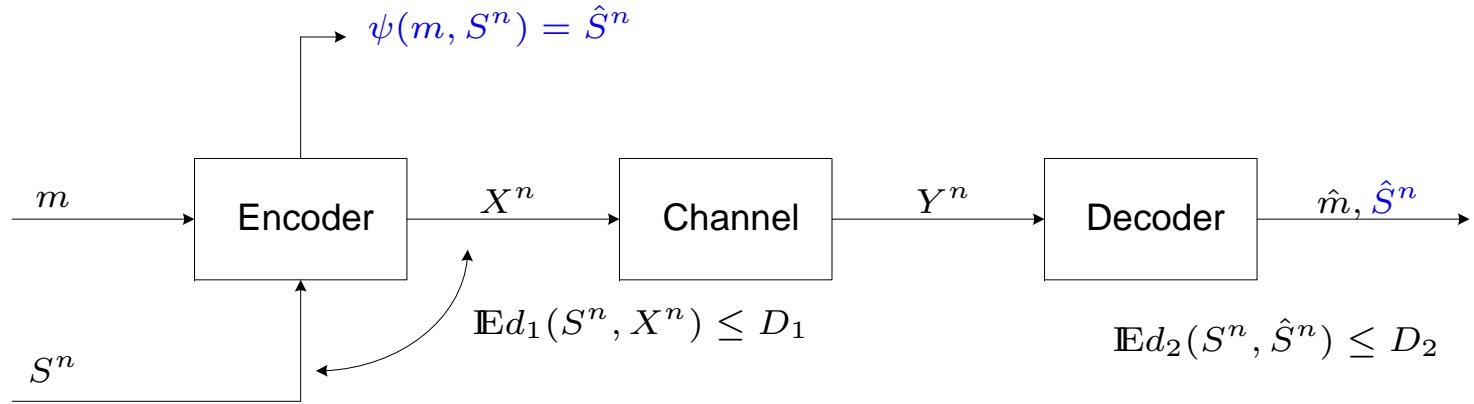
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- ▶ $\max_{\hat{S}} [I(\hat{S}; Y) - I(\hat{S}; S)]$ is achievable, but sub-optimal.
- ▶ Although W (or $\varphi(W)$) is a good source code generated by the encoder, separation is sub-optimal.

Main Result (cont'd)

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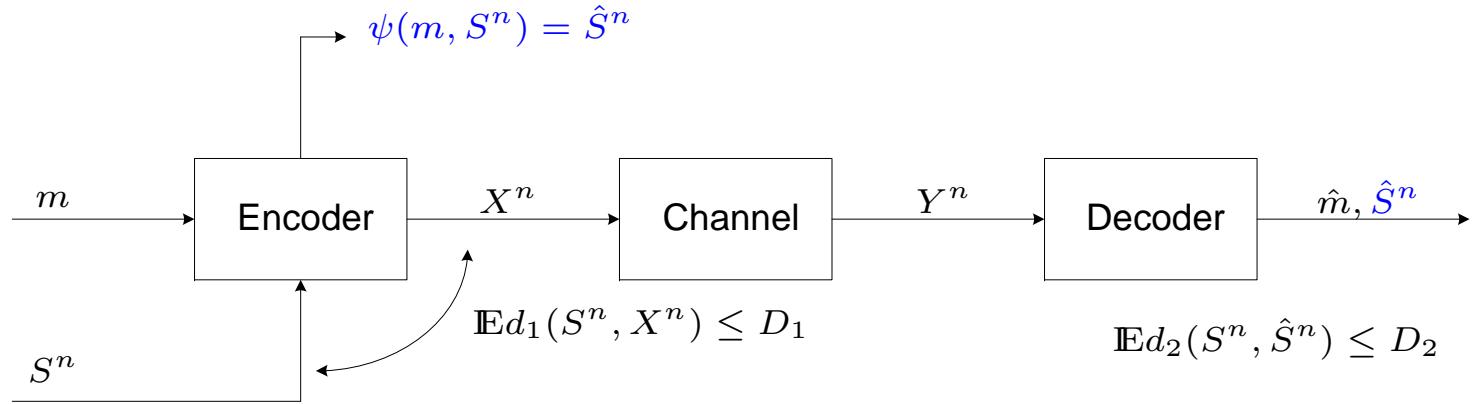
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$$\mathbb{E}d_2(S, \varphi(W)) \leq D_2.$$

- ▶ $\max_{\hat{S}} [I(\hat{S}; Y) - I(\hat{S}; S)]$ is achievable, but sub-optimal.
- ▶ Although W (or $\varphi(W)$) is a good source code generated by the encoder, separation is sub-optimal.
- ▶ The channel can depend explicitly on S ($P_{Y|X,S}$), in which case $W \in (X, S) \in Y$.
⇒ Solves the problem of joint transmission of data and state (Sutivong et. al.) under CK constraint.

Main Result (cont'd)

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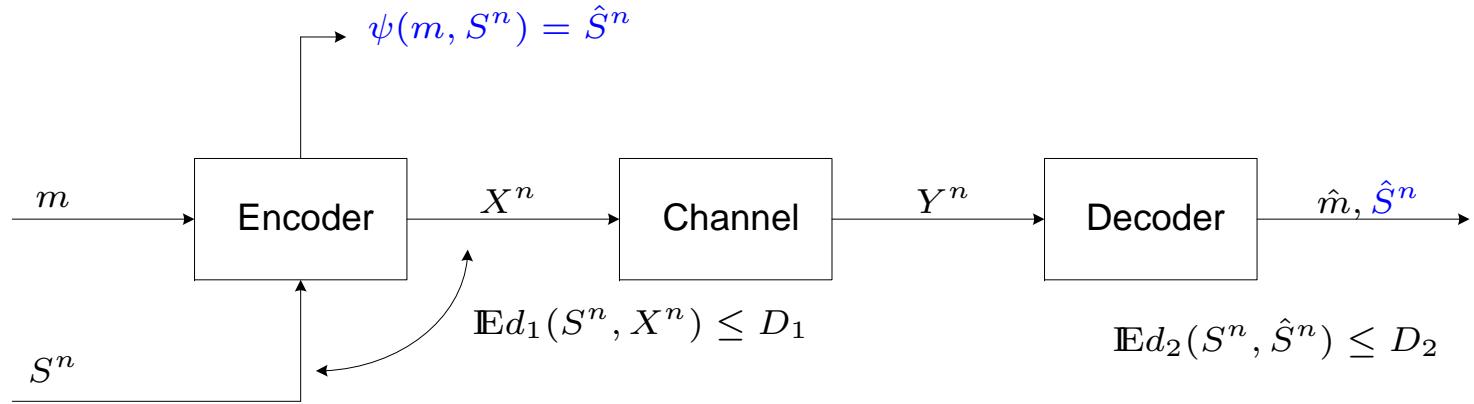
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$$C_{ck}(D) = \max[I(W; Y) - I(W; S)], \quad W \in X \ominus Y$$

$$\mathbb{E}d_1(S, X) \leq D_1,$$

$$\mathbb{E}d_2(S, \varphi(W)) \leq D_2.$$

- ▶ $\max_{\hat{S}} [I(\hat{S}; Y) - I(\hat{S}; S)]$ is achievable, but sub-optimal.
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- ▶ Can bound $|\mathcal{W}| \leq |\mathcal{X}||\mathcal{S}| + 3$.

Example

Example 1 *Binary symmetric channel & host, Hamming distortion measures*

$$Y = X \oplus Z, \quad Z \sim \text{Bernoulli}(p_z), \quad S \sim \text{Bernoulli}(1/2),$$

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Example

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$$\mathbb{E}d_H(S^n, X^n) \leq D_1, \quad \mathbb{E}d_H(S^n, \hat{S}^n) \leq D_2, \quad P(\hat{S}^n \neq \psi(m, S^n)) \leq \epsilon.$$

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1. A separation approach:

$$R_S(D_2) = 1 - h(D_2), \quad C = u.c.e\{g(D_1)\}$$

where

$$g(D_1) = \begin{cases} 0 & 0 \leq D_1 \leq p_z \\ h(D_1) - h(p_z) & p_z \leq D_1 \leq 1/2. \end{cases}$$

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\Rightarrow For $p_z = 0$

$$1 - h(D_2) \leq h(D_1).$$

Example (cont'd)

2. *But for this system, can achieve $D_1 = D_2 = 0$, if we set*

$$X_i = S_i \quad \forall i.$$

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Example (cont'd)

2. But for this system, can achieve $D_1 = D_2 = 0$, if we set

$$X_i = S_i \quad \forall i.$$

In the capacity formula, choose

$$W = X = S, \quad \varphi(W) = \varphi(S) = S.$$

Then $D_1 = D_2 = 0$ are achievable. Moreover

$$I(W; Y) - I(W; S) = I(S; S) - I(S; S) = 0,$$

hence this substitution is valid.

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Thank You!